

**SWAMI
VIVEKANANDASCHOOL OF
ENGG. & TECH.**

MADANPUR, BBSR



LECTURE NOTES

ON

ANALOG & DIGITAL COMMUNICATION

Year & semester: 3RD Year, 5TH Semester

BY- Er. ASHOK KUMAR PRUSTY

**LECTURER IN DEPARTMENT OF ELECTRONICS
& TELECOMMUNICATION ENGINEERING**

Sub-ADC

(Analog & digital communication)

Unit - 1

elements of communication system

NO-1

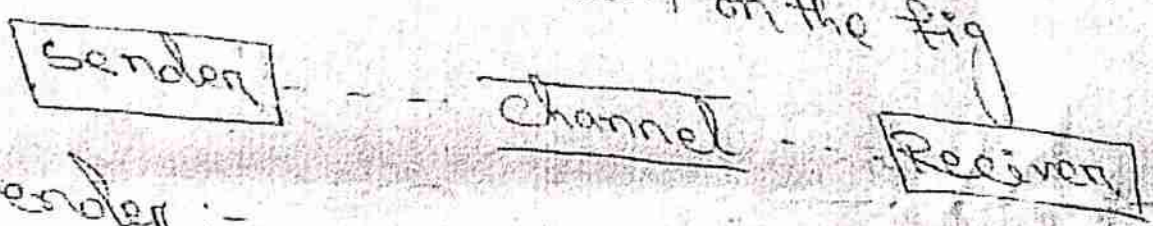
Communication process :- concept of elements of communication system it's block dig.

• what is communication?

Communication can be defined as the process of ex-change of information through means suches, words, action, signals between two or more individuals.

Parts of a communication system.

Any system which provides communication consists of the three important and basic parts as shown on the fig



Sender :-

sender is the person who sends a message. It could be a transmitting station from where the signal is transmitted.

Channel :-

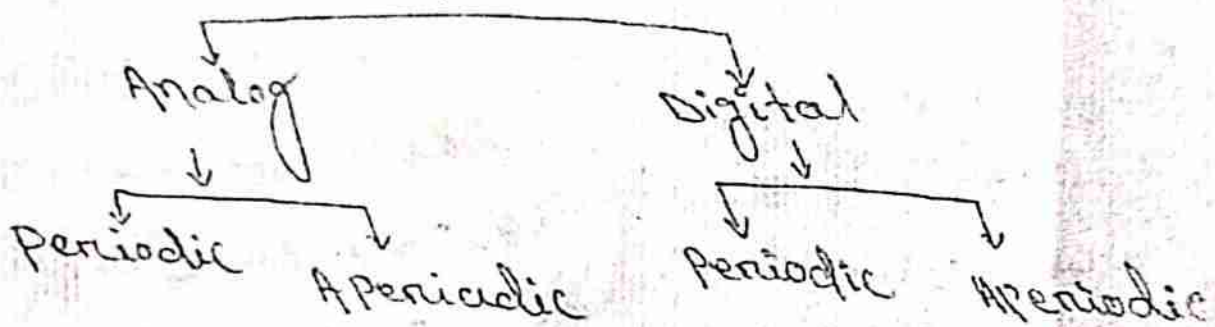
It is the medium through which the message signals travel to reach the destination.

Receiver:

It is the person who receives the messages. It could be a receiving station where the transmitted signal is being received.

Depending on their characteristics, signals are mainly classified into two types: Analog & Digital.

Types of signals



Analog signal:-

A continuous time-varying signal which represents time-varying quantity can be termed as an analog signal. This signal keeps on varying respect to time according to the instantaneous value of the quantity which represents the communication which is based on

analog signal & analog values is called as analog communication.

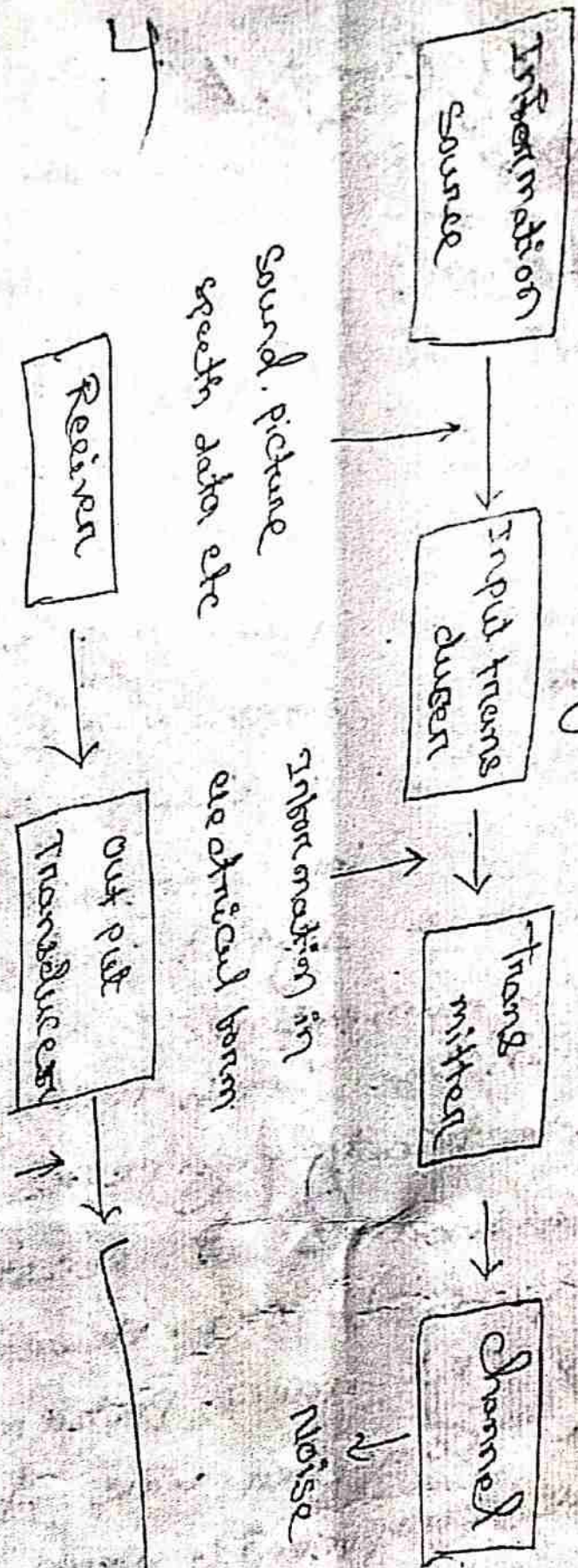
Digital signal:-

A signal which is discrete in nature or which is non continuous in form can be termed as a digital signal. This signal has individual values denoted separately which are not based on the previous value as it they are derived at they particular instants of time.

The communication based on digital signals digital value is called as digital communication.

With the small transition of their hands electrical engineers of the 1950 saw the possibilities of constructing even more advanced crt. However as the complexity of crt grew. Problems arose. One crt time a computer was dependent on crt as the components were large the circuit interconnecting them most being the electric signals took time to go through the crt thus slowing the computer.

Block diagram of communication system



Information in original form

Information Source

As we know in a communication system serves to communicate a message or information

- This information originated in the information source
- In general their can be various message in the form of words group of words code, symbols, sound, signal etc.
- However out of this message only the desired message is selected in communication. We can say that the function of information source is to produce required message which has to be transmitted.

Input transducer:-

→ A transducer is the device which converts one form of energy into another form.

→ The message from the information source may or may not be electrical & in nature. In a case when the message produce by the information source not electrical the information nature and I/P transducer is used to convert it into a time-varying electrical signal.

For Ex:- In case of radio broadcasting a microphone converts the information or message which is in the form of sound waves

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into a corresponding electrical signal.

Transmitter:-

The function of the transmitter is to process the electrical signal from different aspects. For ex:- in radio broadcasting the electrical signal obtained from sound signal, is processed to restrict its range of audio frequencies. All these processing of the message signal are done just to ease the transmission of the signal through channel.

* The channel:-

The term channel means the medium through which the message travels from the transmitter to the receiver. During the process of transmission & reception the signal gets distorted due to noise introduced in the system.

Receiver:-

The main function of the receiver is to reproduce the message signal in electrical form from the distorted received signal. The reproduction of the original signal is accomplished by a process is known as the demodulation. m

Destination :-

Destination is the final stage which is used to convert an electrical message signal into its original form.

For ex:

In radio broadcasting, the destination is a loud speaker which works as a transducer i.e. convert the electrical signal in the form of original sound signal.

Communication Channels :-

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- A communication channel refers either to a physical transmission medium such as wire or to a logical connection over a multiplexed medium such as a radio channel in the communication & computer networking.
- A channel is used to convey an information signal; for ex: A digital bit stream, from one or several senders to one or several receivers.
- A channel has a certain capacity for transmitting information, often measured by its bandwidth in Hz or its data rate in bits per second.
- Communicating data from one location to another requires some form of pathway or medium. These pathways, called communication channels, use two types of media: cable (twisted-pair wire, cable & fibre optic cable)

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Broadcasting microwave, satellite, radio & Infrar. m.
→ Cable or wire line media use physical wires/cables to transmit data & information
→ twisted-pair wire & co-axial cables are made of copper & fiber-optic cables made of glass

Modulation: - Definition
Modulation is the process of changing the parameter of the carrier signal, in accordance with the instantaneous values of the modulating signal.

Need for modulation: -

Base band signals are incompatible for direct transmission. For such a signal, to travel longer distances its strength has to be increased by modulating with a high frequency carrier wave, which doesn't affect the parameters of the modulating signal.

There are 3 basic types of modulation:-

→ Amplitude modulation

→ Frequency modulation

→ Phase modulation

Amplitude Modulation

It's a type of modulation where the amplitude of the carrier signal is modulated in proportion to the message signal while the freq & phase are kept const.

✓ Frequency Modulation

It's a type of modulation where the freq. of the carrier signal is modulated in proportion to the message signal while the amplitude & phase are kept const.

Phase Modulation

It's a type a modulation where the phase of the carrier signal is varied accordance to the law frequency of the message is known as phase modulation

Advantages of modulation :-

- ① Reduction of antenna size
- ② no signal mixing
- ③ Increased communication
- ④ Multiplexing of signals
- ⑤ possibility of bandwidth adjustments
- ⑥ Improved reception quality

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* What is signal:-

signal is a function that conveys information about a phenomena. It refers to any time varying voltage, current or electromagnetic wave that carries information. Ex - music signal

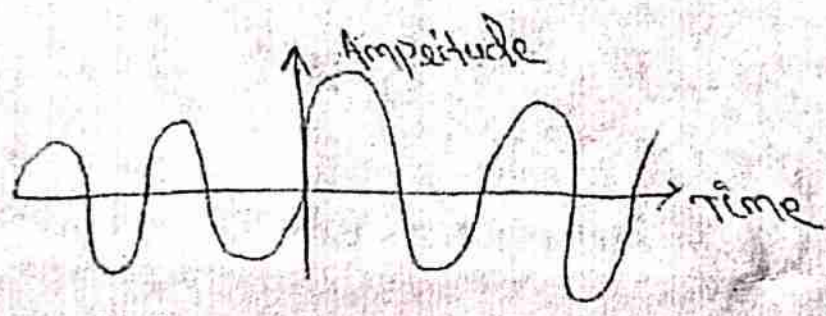
Signal classifications:-

signal can be classified according to many criteria.

- Analog & Digital signal
- Energy & Power signal
- Deterministic & random signal
- even & odd signal

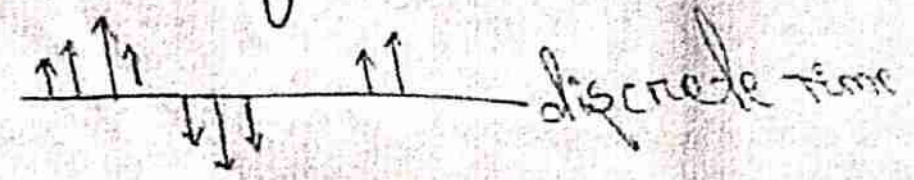
Continuous time & Discrete time signals

A signal said to be continuous when it is defined for all instants of time



Discrete time:-

A signal is said to be discrete when it is defined at only discrete instants of time



Deterministic & Non-deterministic signal

A signal is said to be deterministic if there is no uncertainty with respect to its value at any instant of time



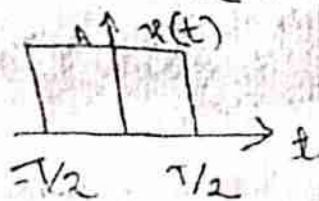
Random signal

A signal is said to be Random signal if there is uncertainty with respect to its value at some instants of time



Even & odd signal:

A signal is said to be even when it satisfies the condition $x(t) = x(-t)$



odd signal:

signal is said to be odd when it satisfies the condition $x(t) = -x(-t)$

Periodic & Aperiodic signal:

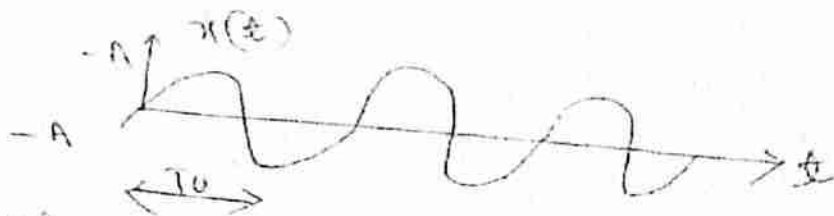
A signal is said to be periodic if it satisfies the condition $x(t) = x(t+T)$ or $x(n) = x(n+N)$

where

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T = fundamental time period

$1/T = F$ = fundamental frequency



The above signal will repeat for every time interval T_0 hence it is periodic with period T_0 .

Energy & Power signals :-

\Rightarrow A signal is said to be energy signal when it has finite energy.

\Rightarrow A signal is said to be power signal when it has finite power.

Note A signal can't be both energy & power simultaneously. Also a signal may be neither energy nor power signal.

Power of energy signal = 0

Energy of power signal = ∞

Real & Imaginary signals :-

\Rightarrow A signal is said to be real when it satisfies the condition $x(t) = x^*(t)$

⇒ A signal is said to be odd when it satisfies the condition $x(t) = -x(-t)$

ex:- If $x(t) = 3$ then $x(-t) = 3 = 3$ hence $x(t)$ is a real signal

If $x(t) = 3j$ then $x(-t) = 3j = -3j = -x(t)$ here $x(t)$ is odd signal

Note For a real signal, Imaginary part should be zero. Similarly for an imaginary signal, real part should be zero.

Bandwidth Limitation:-

Bandwidth refers to how much digital information we can send or receive across a connection in a certain amount of time. Some times it's called data throughput too.

Bandwidth Limits & Issues:-

The term bandwidth limit exceeded means that the amount of bandwidth that was allocated to the hosting plan has been reached. Bandwidth is consumed when data is retrieved from the server & delivered to the end user. Cost bound traces well as when the end user uploads data to the web server (Inbound traffic). All data sent from the site to the client & vice versa gets accounted for and bandwidth usage.

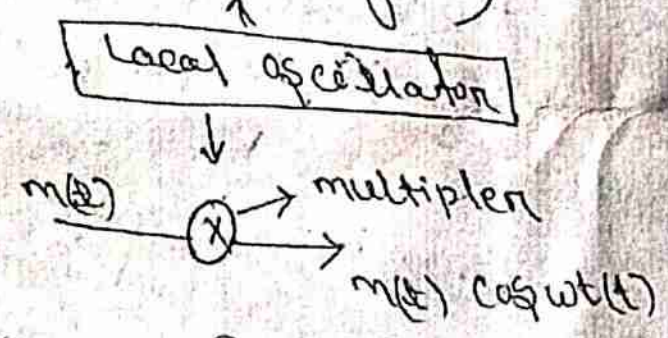
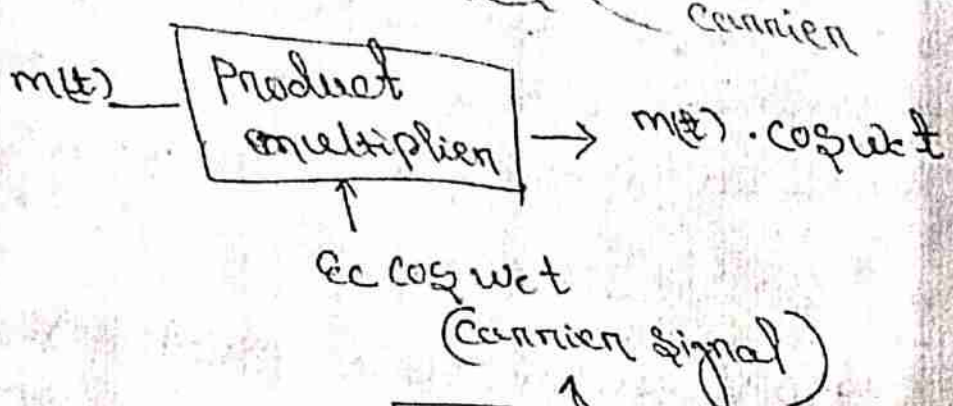
If the amount of bandwidth used exceeds the amount of bandwidth allocated by the web host, the browser will return a bandwidth limit exceeded error.

$$c_n = 2n \omega_c$$

Q/why AM is not efficient modulation:- $\eta = 1/10/20$

Ans:- As we know that the max efficiency $\eta = 33\%$ for $(m=1)$ which is practically very less value. This means 33% of the transmitted power is used for carry the message & rest 67% of the total power used by the carrier is not usable.

Generation of DSBSC (Double side band suppressed carrier)



$m(t)$ \rightarrow modulating signal $E_m \cos w_m t$
 $E_c \cos w_c t$ \rightarrow high frequency carrier generated from local oscillator & the Product modulation function is to multiply the signals. \therefore it can be replaced by a multiplier.

So, now, $m(t)$ & $\cos \omega_c t$ are the two inputs which are multiplied at the multiplier.

So, the multiplier $y(t)$ is

$$m(t) \times E_c \cos \omega_c t \quad (i)$$

$$E_m E_c (\cos \omega_m t, \cos \omega_c t) \quad (ii)$$

$$= \frac{E_m E_c}{2} [\cos(\omega_c + \omega_m)t + \cos(\omega_c - \omega_m)t] \quad (iii)$$

The eqn (3) expressed DSB-SC

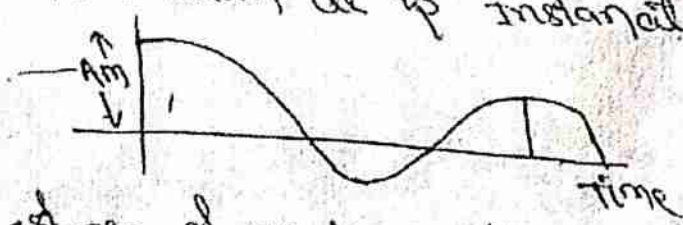
As there are two side bands

$\rightarrow (\omega_c + \omega_m)$ & $(\omega_c - \omega_m)$ so it is

double side band suppressed carrier.

Amplitude (linear) modulation system:-

\rightarrow The amplitude of the carrier signal varies according to the instantaneous amplitude of the modulation signal which means the amplitude of the carrier signal containing known information varies as for the amplitude of the signal containing information it is instant.



\rightarrow The 1st fig shows the modulating which is the message signal \rightarrow the next one is the carrier wave which is a high frequency signal & contains no information. - while the last one is the resultant of modulation wave.

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21-24/11/20

Derivation of Amplitude modulation:-

→ modulation index is also known as modulation is defined for the carrier wave to describe the modulated variable to carrier signal varying with respect to its unmodulated level A_c respectively

$$\mu = \frac{A_m}{A_c}$$

→ Consider maximum & minimum amplitude of the wave as A_{max} & A_{min} .
→ depending upon $\cos(\omega t + \phi)$ following to equation are derived with maximum & minimum amplitude of the modulated waves

$$A_{max} = A_c + A_m$$

$$A_{min} = A_c - A_m$$

$$A_{max} + A_{min} = A_c + A_m + A_c + A_m$$

$$A_{max} + A_{min} = 2A_c$$

② $A_{max} = A_c + A_m$

$$A_{min} = A_c - A_m$$

$$A_{max} + A_{min} = (A_c + A_m) + (A_c - A_m)$$

$$A_{max} + A_{min} = 2A_c \quad \text{--- (1)}$$

$$A_c = \frac{A_{max} + A_{min}}{2}$$

$$A_{max} - A_{min} = (A_c + A_m) - (A_c - A_m)$$

$$A_{max} - A_{min} = 2A_m \quad \dots \quad (ii)$$

$$A_1 = \frac{A_{max} + A_{min}}{2}$$

$$\frac{A_{max} - A_{min}}{2}$$

$$A_1 = \frac{A_m}{A_c}$$

The Power Relation. Amplitude modulation:

→ Consider the following eqn Amplitude modulation wave

$$s(t) = A_c \cos(2\pi f_c t) + \frac{A_c \mu}{2} \cos$$

$$2\pi (f_c + f_m) + \frac{A_c \mu}{2} \cos(2\pi f_c - f_m)$$

→ Power of Am wave is equal to the sum of power of Am carrier upper side band & lower side band free component

$$P_t = P_c + P_{USB} + P_{LSB}$$

→ we know that the standard formula for power of cos signal is

$$P = \frac{V_{rms}^2}{R} = \left(\frac{V_m}{\sqrt{2}}\right)^2$$

→ where

V_m is the rms value of cos signal and

→ 1st let us find the upper side band carrier power $\frac{1}{2}$

Carrier Power:

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$$P_c = \frac{\left(\frac{A_c}{\sqrt{2}}\right)^2}{R}$$

$$P_c \Rightarrow \frac{(A_c/\sqrt{2})^2}{R} \Rightarrow \frac{A_c^2/2}{R} \Rightarrow \frac{A_c^2}{2} \times \frac{1}{R} \Rightarrow \frac{A_c^2}{2R}$$

Upper side band power:

$$\begin{aligned} P_{USB} &= \frac{(A_{cM})^2}{2\sqrt{2}} \\ &= \frac{A_c^2 m^2}{8R} \\ &= \frac{A_c^2 m^2}{8R} \end{aligned}$$

③ Similarly we will get the lower side band power that is the upper side band lower side band power.

$$P_{LSB} = \frac{A_c^2 m^2}{8R}$$

Now let us add their power in order to get power in order to get the AM wave.

$$\Rightarrow P_{\Sigma} = \frac{A_c^2}{2R} + \frac{A_c^2 m^2}{8R} + \frac{A_c^2 m^2}{8R}$$

$$P_{\Sigma} = \frac{A_c^2}{2R} \left(1 + \frac{m^2}{4} + \frac{m^2}{4} \right)$$

$$P_t = P_c \left(\frac{1 + \mu^2}{2} \right)$$

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dt = 25/10/20

Band width of amplitude modulation wave
(frequency range)

Band width is the difference between the highest and lowest frequency of signal mathematically we can write is as

$$BW = f_{max} - f_{min}$$

consider the following eqn of amplitude modulated wave.

$$s(t) = A_c [1 + \mu \cos(2\pi f_m t)] \cos(2\pi f_c t)$$

$$\Rightarrow s(t) = A_c + A_c \mu \cos(2\pi f_m t) \cos(2\pi f_c t)$$

$$\Rightarrow A_c \cos(2\pi f_c t) + \frac{A_c \mu}{2} \cos(2\pi f_m t) \cos(2\pi f_c t)$$

$$s(t) = A_c \cos(2\pi f_c t) + \frac{A_c \mu}{2} \cos[2\pi(f_c + f_m)t] + \frac{A_c \mu}{2} \cos[2\pi(f_c - f_m)t]$$

Hence the amplitude modulated has three frequencies one carrier frequency f_c , upper side band $f_c + f_m$ & lower side band $f_c - f_m$.

Hence

$$f_{max} = f_c + f_m$$

$$f_{min} = f_c - f_m$$

Substitute

f_{max} & f_{min} value in band width formula.

$$\Rightarrow BW = f_c + f_m - (f_c - f_m)$$

$$f_c + f_m - (f_c - f_m)$$

$$= f_c + f_m - f_c + f_m$$

$$= 2f_m$$

Thus it can be said that the bandwidth required for amplitude modulated wave is twice the frequency of the modulating signal.

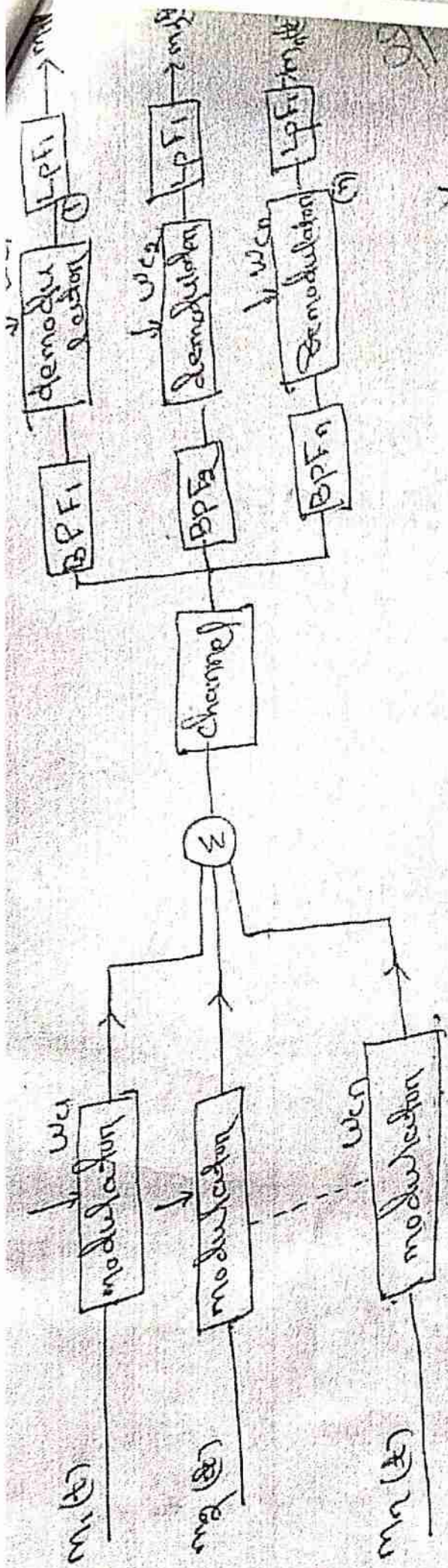
Frequency division multiplexing: dt = 3/10/20

It is a technique in which several message signals combine into a composite signal for transmission over a common channel.

→ But to transmit those signals in a same channel the signals must be kept a path from each other. In terms of their frequency ranges. So that those signals do not interfere among each other.

⇒ Consider $m_1(t)$ is a message signal & these modulated by carrier frequency ω_{c1} in terms of kHz (Assuming) 100 kHz. m_2 is another message signal & it modulated by a carrier freq ω_{c2} (200 kHz)

Like this the resultant modulation signals are added & transmitted through a common channel & which will not be interfere. due to this is a



huge gap betn to modulated signal

→ Then the modulated signal passes through band pass filter corresponding to the frequency range of the modulating signal $s_{m1}(t)$ modulating signal passes through BPF₁ & demodulated with the help of again ω_{c1} & passes through LPF₁. So the final result will be $m_1(t)$.

→ Similarly for $m_2(t)$ BPF₂ demodulation 2 So the final result will be $m_2(t)$.

→ FM is basically used in telephone system & cable TV

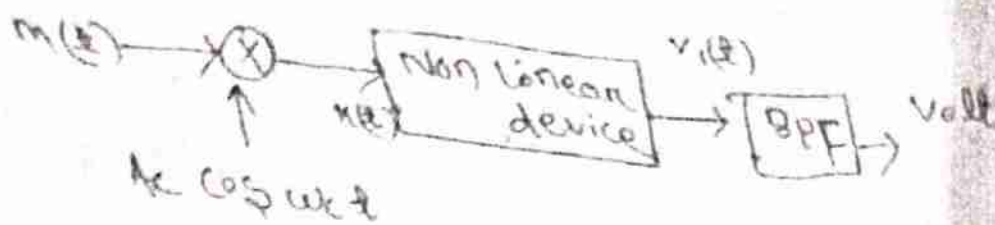
→ In case of AM broadcasting the carrier frequency is 20 kHz & in FM broadcasting the carrier freq. is 90 MHz

Generation of AM or DSB signal :-

Two methods are there

- ① Power law AM modulation
- ② Switching AM modulation

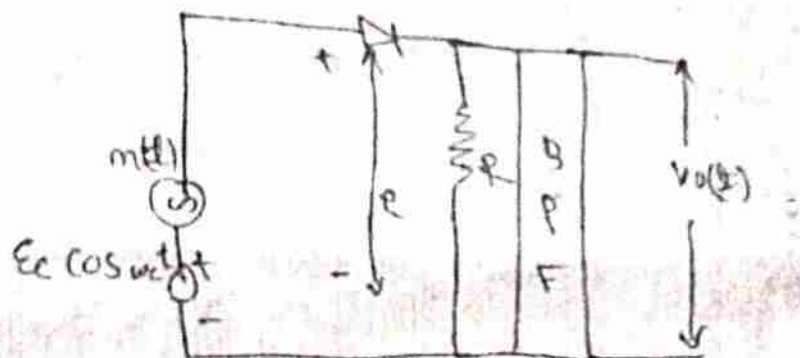
* Power law AM modulation



output of the circuit is $m(t) + Ac \cos wt$ for non-linear device

$$y = ax + bx^2$$

$$v_1(t) = a [m(t) + Ac \cos wt] + b [m(t) + Ac \cos wt]^2$$



Now passing the signal to the BPF the analysis is shown below

- > Here R is only multiplied as a type of constant
- > In this diode is used as a non-linear device from the above circuit

$$e = [m(t) + E_c \cos wt] \text{ by applying KVL}$$

we know that
 $i = a e + i_{s2}$

$$= a [m(t) + E_c \cos \omega_c t] + b [m(t) + E_c \cos \omega_c t]$$

we know that

$$V_o(t) = iR$$

$$= R [a (m(t) + E_c \cos \omega_c t) + b (m(t) + E_c \cos \omega_c t)]$$

$$= R a [m(t) + E_c \cos \omega_c t] + R b [m(t) + E_c \cos \omega_c t]$$

$$= R a m(t) + R a E_c \cos \omega_c t + R b m(t) + R b E_c \cos \omega_c t$$

$$= R a E_m \cos \omega_m t + R a E_c \cos \omega_c t + R b E_m \cos \omega_m t + R b E_c \cos \omega_c t$$

→ when $V_o(t)$ is input to the BPF which has a centre frequency ω_c which means it will pass $(\omega_c + \omega_m)$ & $(\omega_c - \omega_m)$. So in both the upper end & the lower end the passes frequency should be high

(Since both the ends contain ω_c which means high freq)

Note And the suppressed part the $R a E_m \cos \omega_m + R b E_m \cos \omega_m$ & these two signals contain low freq (ω_m) & finally the output is i.e. $a R E_c \cos \omega_c t + b R E_c \cos \omega_c t$

$$= a R E_c \cos \omega_c t + b R (\cos \omega_c t + \cos \omega_m t)$$

$$= \underbrace{k_1 E_c \cos \omega_c t}_{\text{Carrier}} + \underbrace{k_2 \cos(\omega_c + \omega_m)}_{\text{DSB-SC signal}} t$$

$$\therefore k_1 = aR$$

$$k_2 = bR$$

→ which is AM (or carrier + DSB-SC signal)

SSB-SC

DA = 28/9/2020

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For SSB-SC single side band & single carrier

$$BW = F_m \text{ (for single side band)}$$

$$\rightarrow \text{when } m < 1 \quad \frac{A_m}{A_c} < 1$$

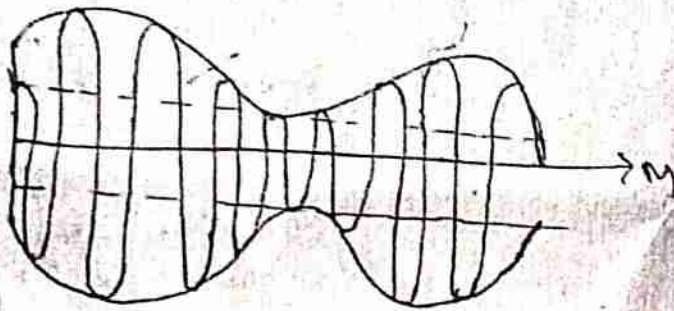
$$\frac{E_m}{E_c} < 1$$

$$A_m < A_c$$

$$\text{Let } m = 0.5 < 1$$

$$\eta = \frac{m^2}{2+m^2} \times 100$$

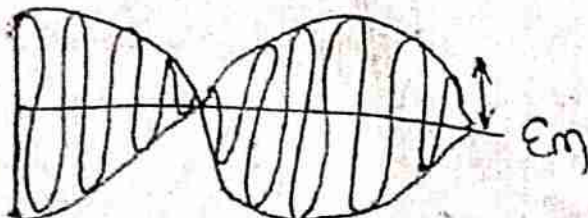
$$\frac{(0.5)^2}{2+(0.5)^2} \times 100$$
$$= 11.11\%$$



For $m=1$

$$A_m = A_c$$

$$\eta = \frac{m^2}{2+m^2} = \frac{1}{3} \times 100 = 33.33\%$$



$$m=1$$

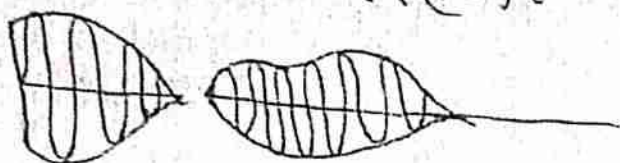
For $m > 1$

$$= \frac{A_m}{A_c} > 1$$

$$= A_m > A_c$$

Here let $m = 1.5$

$$\eta = \frac{m^2}{2 + m^2} = \frac{(1.5)^2}{2 + (1.5)^2} \times 100 = 57\%$$



→ In this case $m > 1$ some part of the information are lost so the exact information is not possible to get so modulation index can't be taken for $m > 1$ & it should be:

SSB-SC (single side band suppressed carrier signal)

→ It carrier & one side band is suppressed no information is lost so it makes the advantage of transmission as less band width.

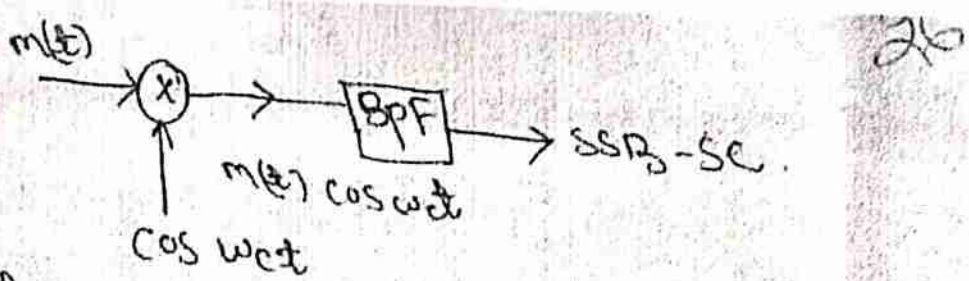
Generation:

- 1- By filter method
- 2- By phase shift method

1- By filter method:

→ It is most commonly used

→ In this method a the SSB-SC signal is passed through a sharp cut-off filter to eliminate any one side band



⇒ The gp of the multiplier is $m(t) \cdot \cos \omega_c t$

$$= E_m \cos \omega_m t \cdot \cos \omega_c t$$

$$= \frac{E_m}{2} [\cos(\omega_c + \omega_m)t + \cos(\omega_c - \omega_m)t]$$

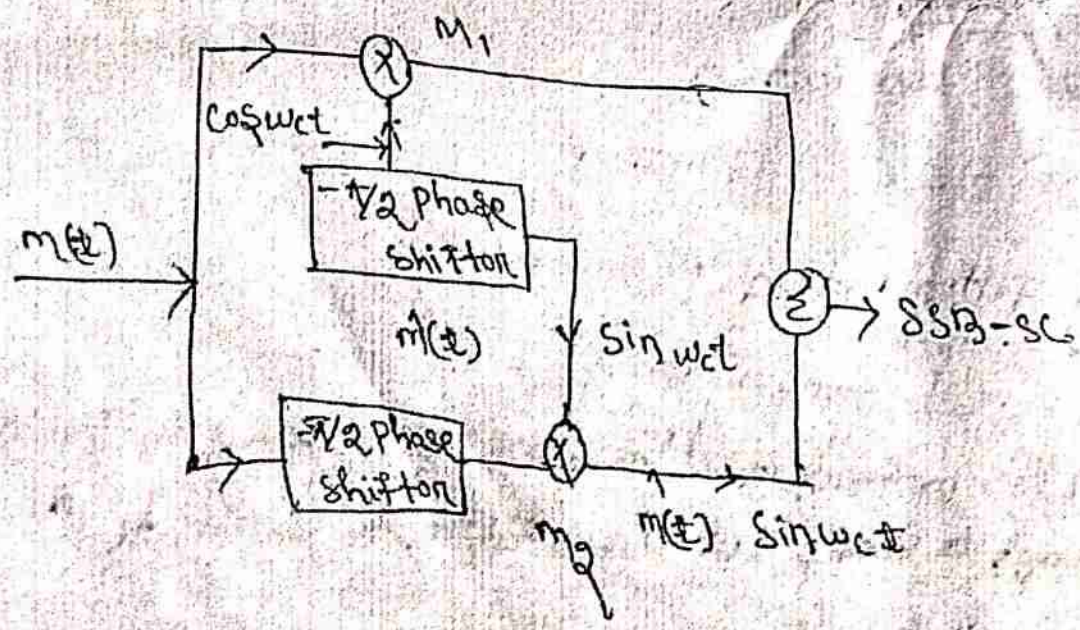
$$= \frac{E_m}{2} \cos(\omega_c + \omega_m)t + \frac{E_m}{2} \cos(\omega_c - \omega_m)t$$

⇒ Here the band pass filter is a special filter frequency (So it is called sharp cut off BPF)

⇒ If the band pass filter has a cut-off freq $(\omega_c + \omega_m)$ then USB (Upper side band) will be passed i.e. $\frac{E_m}{2} \cos(\omega_c + \omega_m)t$ will be passed.

⇒ But it is very difficult to pass completely by a signal.

Phase shift method:



For m_1 multiplier the I/p signals are $m(t) \& \cos \omega_c t$
and the o/p is $m(t) \cos \omega_c t$.

For m_2 multiplier the I/p signals are $\sin \omega_c t \& \hat{m}(t)$
 $\cos \omega_c t$ is phase shifted by $-\pi/2$
which means $\cos \omega_c t \cdot -\pi/2 = \sin \omega_c t$

But here the $m(t) = E_m \cos \omega_m t$ after $\pi/2$ phase
shifter it becomes $\hat{m}(t)$ i.e. $E_m \sin \omega_m t$. So the
final o/p for $m_2 = \hat{m}(t) \cdot \sin \omega_c t$
 $= E_m \sin \omega_m t \cdot \sin \omega_c t$

Finally o/p of $m_1 \& m_2$ is
 $m(t) \cdot \cos \omega_c t + \hat{m}(t) \cdot \sin \omega_c t$

$$= E_m \cos \omega_c t \cdot \cos \omega_c t + E_m \sin \omega_m t \cdot \sin \omega_c t$$

We know that:-

$$\cos(A \mp B)$$

$$= \cos A \cdot \cos B \pm \sin A \cdot \sin B$$

$$= E_m \cos(\omega_m(t) \mp \omega_c(t))$$

$E_m \cos(\omega_c t - \omega_m t) \rightarrow$ lower side band
which is USB - SC signal
 $E_m \cos \omega_c t + \omega_m t \rightarrow$ upper side band

I/p to the multiplier are $m(t) \cos \omega_c t + \hat{m}(t) \sin \omega_c t \cdot \cos \omega_c t$. So the o/p of the multiplier is
 $m(t) \cos^2 \omega_c t + \hat{m}(t) \sin \omega_c t \cdot \cos \omega_c t$

$$= \frac{m(t)}{2} (\cos 2\omega_c t) + \frac{\hat{m}(t)}{2} (\sin 2\omega_c t)$$

$$= \frac{E_m \cos \omega_m t}{2} (\cos 2\omega_c t + \frac{E_m \sin \omega_m t}{2} \sin 2\omega_c t)$$

$$= \frac{E_m}{2} (\cos^2 \omega_m t \cdot \cos 2\omega_c t + \sin \omega_m t \cdot \sin 2\omega_c t)$$

When this is passed through low pass filter it has cut-off freq, ω_m so only $\cos \omega_m t$ will be passed & rest of the signal are suppressed by the low pass filter.

VSB-SC (Vestigial " side band suppressed)

→ When a signal contains high frequency component the USB & LSB tends to need the carrier frequency. Under such condition it is very difficult to isolate one side band from the other. So to overcome this difficulty VSB technique is used, which in state of a rejecting on side band completely, gradual cutoff of one side band is allowed & this cut off is compensated by vestige / on some portion of the other side band.

Angle Modulation:

→ Angle modulation comprises of phase modulation & frequency modulation. This refers to the process by which the phase angle of the carrier signal is varies in accordance with the modulation signal or message signal.

Angle modulation: The process of changing phase modulation means both the phase & frequency modulation of the carrier signal is varied in accordance to the instantaneous value of modulation signal. Keeping the amplitude constant is a angle modulation.

Let us consider an unmodulated carrier wave.

$$\begin{aligned}\phi(t) &= E_c \cos(\omega_c t + \phi_0) \\ &= E_c \cos \phi t\end{aligned}$$

$$\Rightarrow \phi(t) = \omega_c t + \phi_0$$

Now differentiating with respect

$$\frac{d\phi(t)}{dt} = \omega_c$$

$\omega_c \Rightarrow$ Here is the frequency which is the dependent.

Now time dependent angular velocity.

is called instantaneous angular frequency.

$$\omega_i(t) = \frac{d\phi(t)}{dt}$$

$$\int \omega_i(t) dt = \phi(t)$$



Phase modulation:

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The process of changing the instantaneous phase linearly with baseband signal about an unmodulated phase $\omega_c t$ keeping the amplitude & frequency constant.

Again let us consider a carrier signal

$E_c \cos \omega_c t$ we know that

$$\psi(t) = (\omega_c t + \phi_0) + k_p m(t) \quad \text{--- (i)}$$

Assuming the angle to ϕ_0 at particular instant

$$\phi_0 = 0 \quad \text{so}$$

$$\psi(t) = \omega_c t + k_p m(t)$$

Here k_p represents the phase sensitivity constant. So the expression for phase modulation

$$\begin{aligned} e_{pm}(t) &= E_c \cos \psi(t) \\ &= E_c \cos [\omega_c t + k_p m(t)] \quad \text{--- (ii)} \end{aligned}$$

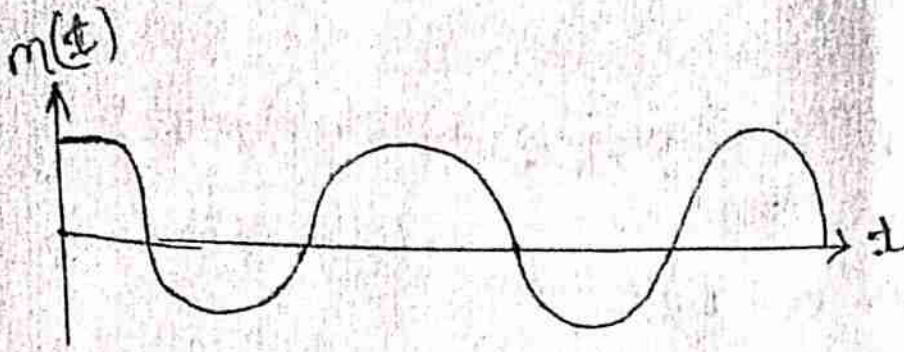
Frequency Modulation:

→ it is defined as the instantaneous respect to baseband signal unmodulated ω_c carrier frequency ω_c

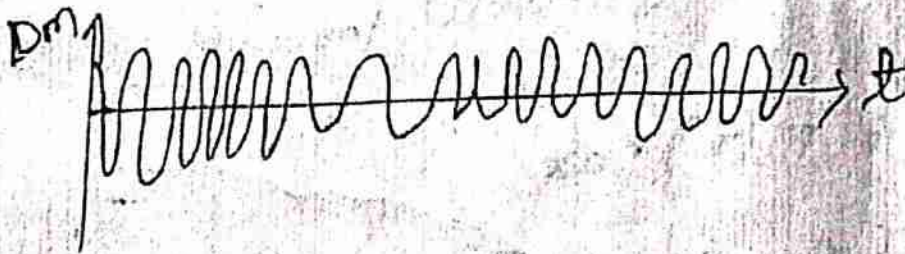
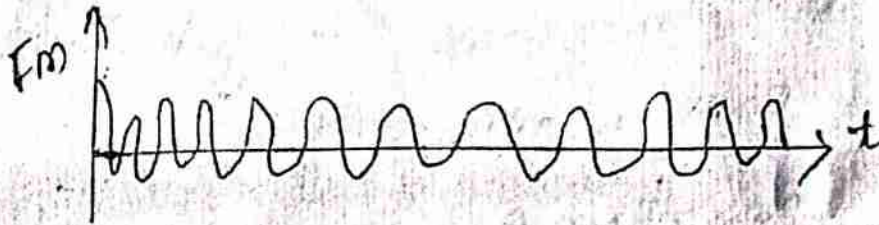
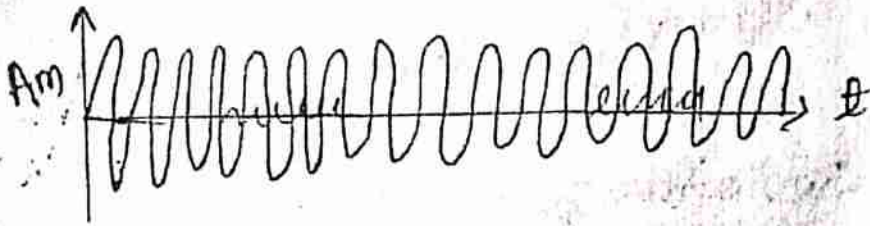
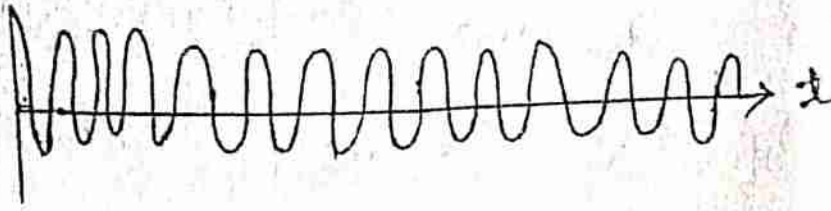
The frequency of the carrier employs means some times compression takes place in the time cycle of $m(t)$ & some time expansion takes place of the changes according to the modulating.

Diagram

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Carrier



The instantaneous angular freq. in freq. modulation is $\omega_i(t) = \omega_c t + k_f m(t)$

k_f is the frequency sensitivity constant but we know that

$$\psi_i(t) = \int \omega_i(t) dt$$

$$= \int \omega_c(t) + k_f m(t)$$

$$= \omega_c(t) + \int k_f m(t)$$

$$= \epsilon_c \cos \omega_c(t) + \int k_f m(t)$$

$+ k_f m(t)$

$$\epsilon_c \cos \left[\omega_c(t) + \int k_f m(t) \right]$$

Frequency deviation:

It is defined as the maximum change in instantaneous ω_c carrier frequency

$$\Delta \omega = |\omega_i - \omega_c|_{\max} = |\omega_c(t) + k_f m(t) - \omega_c(t)|_{\max}$$
$$= |\omega_c(t) + k_f m(t) - \omega_c(t)|_{\max}$$

$$\Delta \omega_1 = k_f m(t)_{\max}$$

$$= k_f \epsilon_m \cos \omega_{ml} \max$$

So to have max^m value take $\cos \omega_{ml} = 1$
So it will be

$$\Delta \omega = k_f \cdot \epsilon_m$$

Modulating Index:

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→ It is the ratio of frequency deviation to the frequency of modulation signal.

→ It is denoted by $\beta = \frac{\Delta\omega}{\omega_m}$

→ β is always greater than standard effect.

* $\psi_i(t) = \omega_c(t) + k_f \int m(t) dt$

* $\psi(t) = \omega_c(t) + k_f \int E_m \cos \omega_m(t) dt$

* $\omega_c(t) + k_f E_m \int \cos \omega_m(t) dt$

* $\omega_c(t) + k_f \sin \omega_m(t)$

* $\omega_c(t) + k_f \frac{E_m}{\omega_m} \sin \omega_m t$

* $\omega_c(t) + \beta \sin \omega_m t$

→ Since $\beta =$ the modulating Index of FM

$$E_{FM}(t) = E \cos [\omega_c t + \beta \sin \omega_m t]$$

Types of frequency modulation:

- ① wide band frequency modulation (WBFM)
- ② narrow band frequency modulation (NBFM)

WBFM

When the value of modulating Index the large number of side band are produce because the Bandwidth produce.

$$\text{If } \beta > 1$$

$$\neq \Delta F > 1$$

$$\therefore \beta = 2(F_m + \Delta F)$$

$$\Rightarrow 2\Delta F$$

$$\frac{\Delta F}{F_m} > 1 \quad \beta > 1$$

$F_m = 0$ wide BFM

$\Delta F = 0$ NBFM

NBFM:-

When the value of modulation Index is small hence it is called frequency modulation then the Band width is

$$\Rightarrow \frac{\Delta F}{F_m} > 1$$

$$\therefore \beta w = 2(F_m + \Delta F)$$

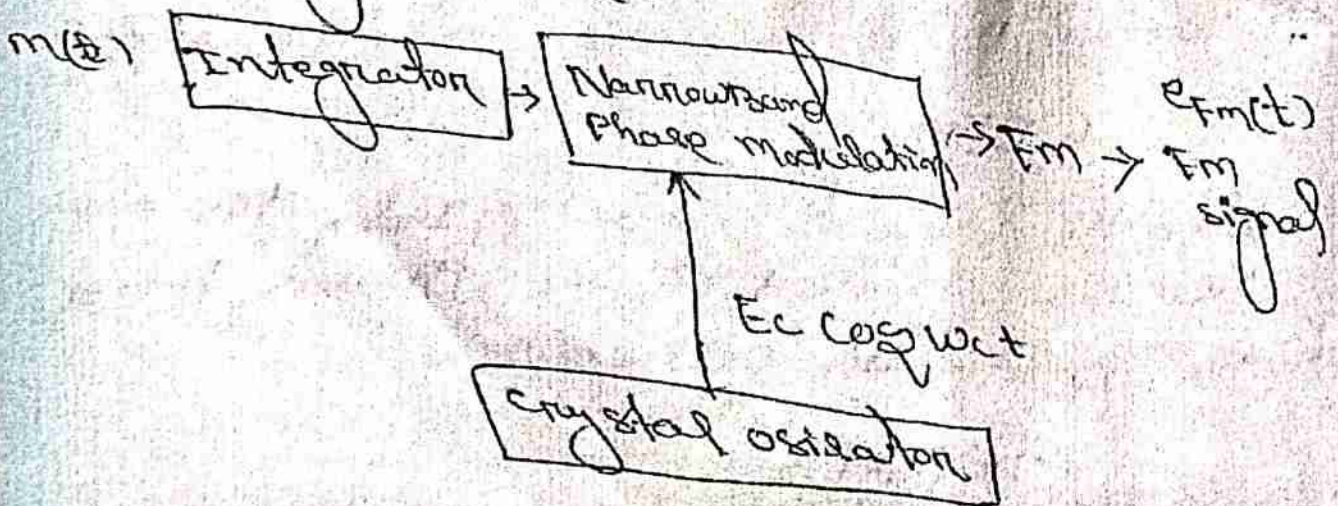
$$= > 2F_m$$

Due to small BW deviation in NBFM is less.

Generation of frequency modulation:-

- ① Armstrong method
- ② Parameter variation method

③ Armstrong method:-



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this is an indirect method of generation, absolute
Band FM is ~~was~~ proposed by Armstrong.
but in this method we have to generate NBFM first.
Here the μ_p is $M(t)$ is passed through integration,
which message signal is

26.10.20

Frequency modulation & Amplitude modulation
Advantage & Disadvantage

Advantage of FM over AM:-

The Amplitude of an FM wave remains constant over time this allows the encoders & decoders the freedom to remove the noise from the received signal. This is done with the assistance of a filter that removes signal of wave length greater than that of the transmitted signal thereby removing the noise. Immune systems since the AM signal transmitted. Information of the wave form can't be altered.

→ In AM systems: the power consumption for signal transmission is higher when compared to FM systems. In AM systems the power depends on the modulation index also called "MI" when MI reaches unity the power consumption is 100%.

In FM system the power of the transmitted signal is proportion to the Amplitude of the unmodulated carrier signal & it is constant therefore FM is always more power efficient than AM system.

→ In FM systems the frequency deviation of the signal is related to the noise ratio. A higher frequency deviation means that the base band signal can be easily retrieved from the FM signals.

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where as less deviation means it is harder to separate the data from the noise. In AM systems the only method of reducing noise is the transmission, is the increase in the transmission power of the signal which increases the cost of operation of the AM system.

→ In an AM system there is no ground bond in between two adjacent channels. This seriously increases the occurrence of interference of AM radio station unless one signal is strong enough to overpower the other where as in the case of FM signal. The adjacent FM channels are separated by ground bonds which result in very little interference between adjacent FM channels.

Dis Advantages of FM over AM

- The equipment needed for FM & AM system is different. The equipment cost of an FM channel is more complex & involves complicated circuiting. As a result FM systems are costlier than AM systems.
- FM system work using a line of sight propagation whereas AM systems use sky wave propagation consequently the receiving area of an FM system is much smaller than that of AM & FM antenna for FM systems need to be close by where as AM systems can communicate with other system through the world by reflected signals off the ionosphere.
- In an FM system there is infinite no of side bands resulting in a theoretical bandwidth

on fm signal being in the this band width is limited by Carson's rule but it is still much larger than that of an fm system. In an fm system the bandwidth is only twice the modulation frequency this is another reason why fm systems are costlier than am systems.

42) Armstrong

Then the o/p of the modulator of $f_m(t)$ is the i/p to the phase modulator. The funⁿ is to phase modulate the signal $f_m(t)$ with the help of crystal oscillator whose o/p is $E_c \cos \omega_c t$ so the final o/p of NBPM is $E_c \cos(\omega_c t + k_f f_m(t))$

* This can also be written as $E_c \cos \omega_c t + \beta_1 \sin \omega_c t$
 * This signal is called NBPM signal and here the modulation index is β_1 which is very low.

* To get WBFM on standard which so the signal is passed through the frequency multiplier. The funⁿ of frequency multiplier used to increase the carrier freq as well as the frequency deviation.

* So its frequency modulation is of order 2 which means $[x^2]$ is used as the carrier frequency deviation will be $2\Delta\omega_1$

* By taking nth order frequency multiplier $n\omega_c$ so the final o/p will be $E_c \cos(n\omega_c t + n\beta_1 \sin \omega_c t)$

Demodulation of FM :-

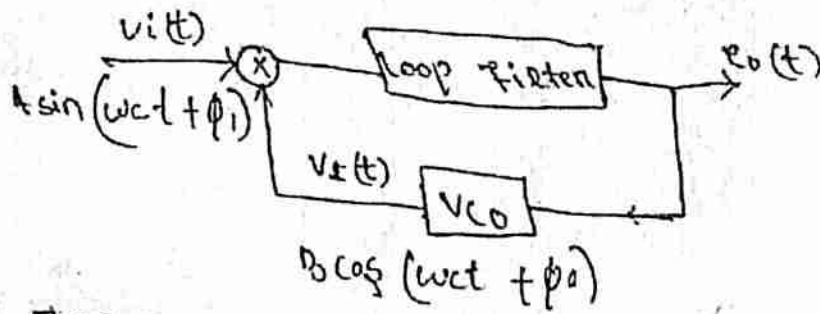
There is the 3 methods demodulation of FM

1) PLL method (Phase locked)

2) Limiter discriminator method

3) Slope detector method

PLL method :-



The incoming signal is FM signal which is

$$A \sin [\omega_c t + \phi_i]$$

$$\phi_i = k \int m(t) dt$$

→ PLL consist 3 main components :-

- ① multiplier
- ② loop filter
- ③ voltage control oscillator

① Multiplier :-

Its function used to multiply incoming signal $A \sin(\omega_c t + \phi)$ with the feedback signal $B \cos[\omega_c t + \phi]$ which is the op of VCO

→ it is also used as phase compensation

② Loop filter :-

It is a narrow band LPF which suppress the high frequency component.

③ Voltage Control Oscillator :-

It is a sine wave generator whose frequency is determined by the applied voltage to it from the external source.

$$e_o(t) / \omega_c(t) = \omega_c \text{ then } e_o(t)$$

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where $\omega_c = \text{o/p freq. of VCO when applied } V_o(t) \text{ voltage.}$

$\omega_c =$ it is the natural frequency when no voltage is applied.

\Rightarrow One important property of the o/p of VCO is 90° phase shift of I/P to it.

Description:-

\rightarrow Initially $m(t) = 0 \& e_o(t) = 0$ at the time VCO has been adjusted such that the frequency of VCO is set at carrier frequency ω_c .

\rightarrow VCO o/p i.e. $V_c(t)$ is phase quadrature of carrier wave.

\Rightarrow Now the incoming I/P signal

$$A \sin(\omega_c t + \phi_0) = A \sin[\omega_c t + k \int m(t) dt]$$

which means I/P signal and the o/p of VCO is

$B \cos[\omega_c t + \phi_0(t)]$ so the o/p of multiplier is

$$A \sin[\omega_c t + k \int m(t) dt] \cdot B \cos[\omega_c t + \phi_0(t)] = A \sin x \cdot \cos y$$

$$\Rightarrow \frac{AB}{2} \sin[2\omega_c t + \phi_1 + \phi_0] + \sin[\phi_1 - \phi_0]$$

$$\frac{\sin(x+y)}{2} + \frac{\sin(x-y)}{2} = \sin x \cdot \cos y$$

$$\Rightarrow \sin(x+y) + \sin(x-y)$$

$$\Rightarrow 2 \sin x \cdot \cos y$$

After passing the o/p of multiplier through which suppresses high freq. component so the o/p of the filter is

$$\frac{AB}{2} [\phi_1 - \phi_0]$$

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$$\Rightarrow \text{Let } (\phi_i - \phi_o) = \phi_e$$

Where $\phi_e = \text{Phase Error}$ & this should be very less

\Rightarrow hence we consider

$$\phi_e = 0$$

$$\Rightarrow 0 = \phi_i - \phi_o$$

$$\phi_i = \phi_o$$

$$\Rightarrow \phi_i(t) = \phi_o(t)$$

we know that $\phi_o(t) = K \int m(t) dt$

Therefore $A \sin[\omega_c t + \phi_i(t)] \cdot B \cos[\omega_c t + \phi_o(t)]$

\Rightarrow The o/p of VCO means the o/p frequency

$$\therefore \omega(t) = \omega_c + k_e m(t) \quad \text{--- (1)}$$

which is also called as the instantaneous frequency of F_c

\Rightarrow Therefore the o/p of VCO is

$$B \cos(\omega_c t + \phi_o(t))$$

Let $\psi(t) = \omega_c t + \phi_o(t)$

$$\frac{d\psi(t)}{dt} = \omega_c + \frac{d\phi_o(t)}{dt}$$

$$\omega(t) = \omega_c + \frac{d\phi_o(t)}{dt} \quad \text{--- (2)}$$

These two eqn (1) & (2) are both o/p for VCO

$$\omega_c + k_e m(t) = \omega_c + \frac{d\phi_o(t)}{dt}$$

Hence, $k_e m(t) = \frac{d\phi_o(t)}{dt}$

$$k_e m(t) = \frac{d}{dt} \left[\frac{1}{k_f} \int m(t) dt \right]$$

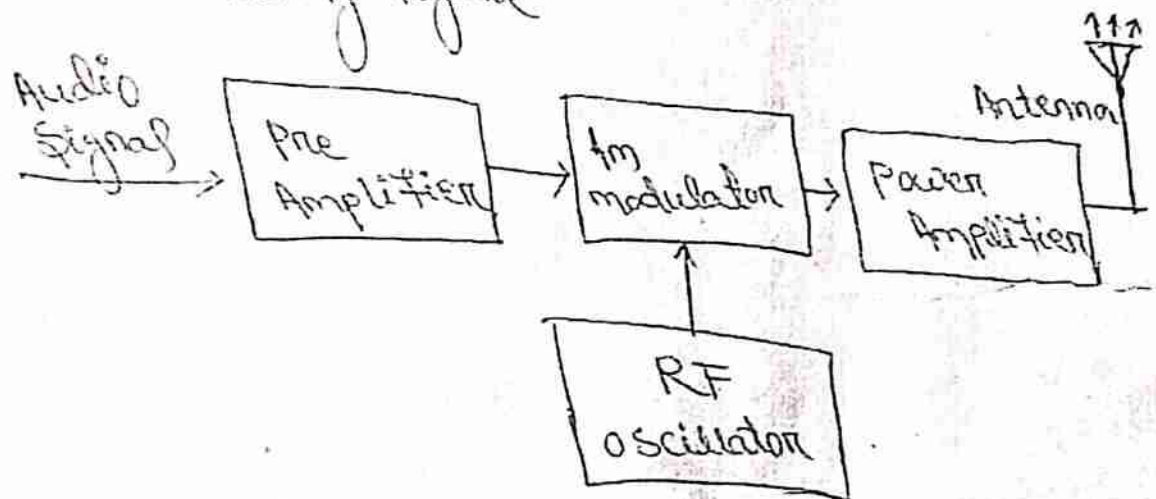
$$K_1 E_o(t) = K_f m(t)$$

Chapter 3

Am Transmitter

Am transmitter takes the audio signal as an I/P and delivers amplitude modulated wave to the antenna as an O/P to be transmitted.

The block diagram of Am transmitter is shown in the following figure



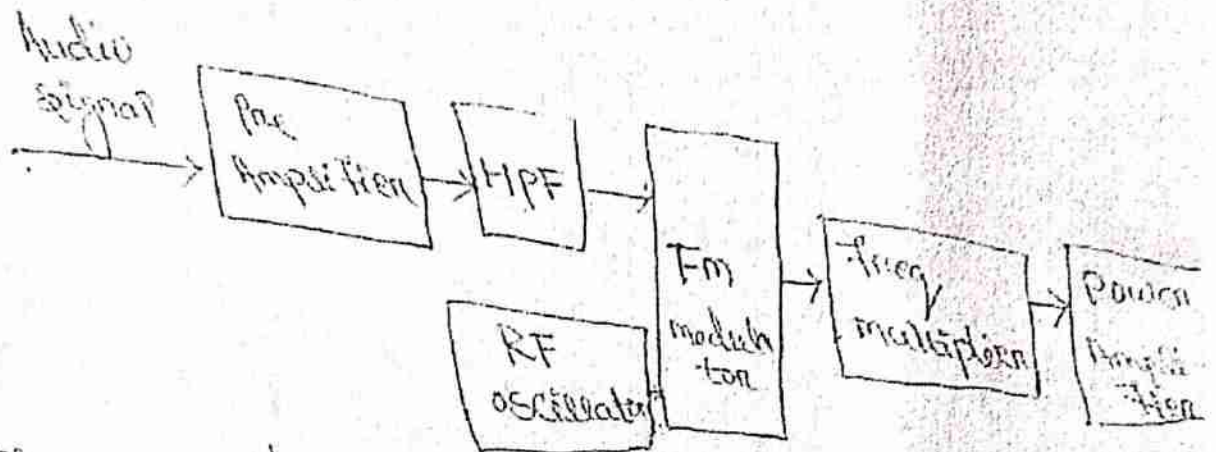
The working of Am transmitter can be explained as follows.

- The audio signal from the O/P of the microphone is sent to the pre-amplifier, which boosts the level of the modulating signal.
- The RF oscillator generates the carrier signal.
- Both the modulating & the carrier signal is sent to Am modulator.
- Power amplifier is used to increase the power levels of Am wave. This wave is finally passed to the antenna to be transmitted.

FM Transmitter

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FM Transmitter is the whole unit which takes the audio signal as an i/p and delivers the wave to the antenna as an o/p to be transmitted. The block diagram of FM Transmitter is shown in the following figure.



The working of FM transmitter can be explained as follows.

- The audio signal from the o/p of the microphone is sent to the pre-amplifier which boosts the level of the modulating signal.
- This signal is then passed to high pass filter which acts as a pre-emphasis network to filter out the noise & improve the signal to noise ratio.
- This signal is further passed to the FM modulator circuit.
- The oscillator circuit generates a high freq carrier which is sent to the modulation along with the modulating signal.
- Several stages of frequency multiplication are used to increase the operating freq.

Even then, the power of the signal is not enough to transmit hence a RF power amplifier is used at the end to increase the power of the modulated signal. This FM modulated φ is finally passed to the antenna to be transmitted.

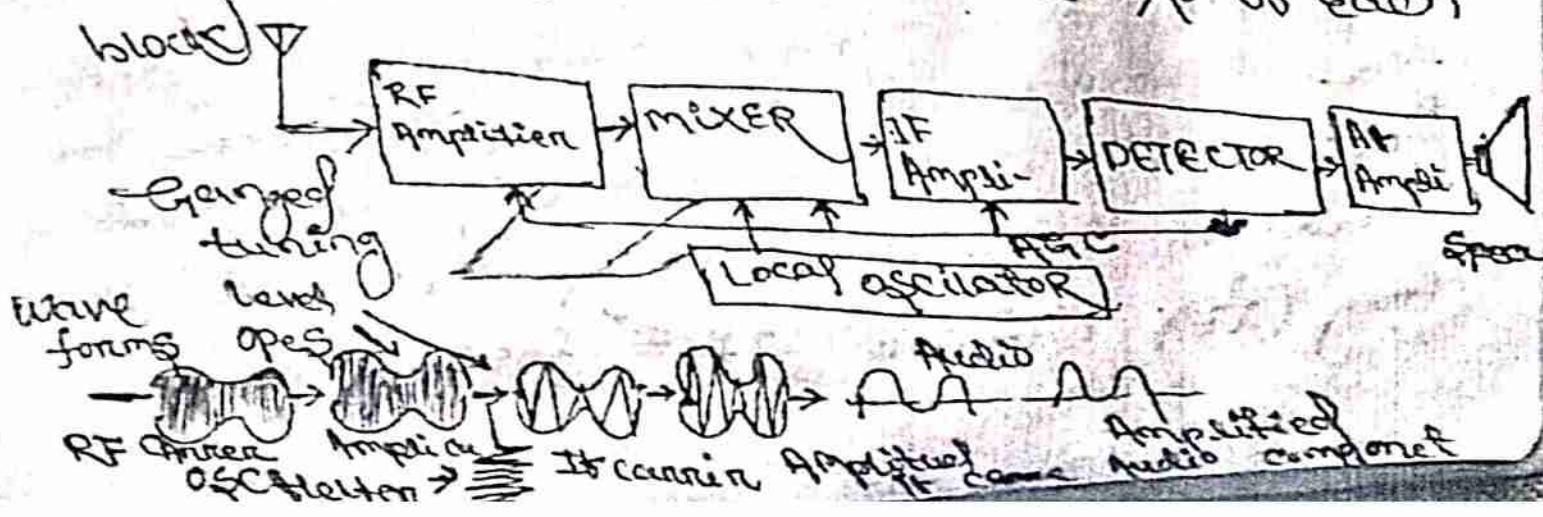
Superheterodyne FM

Superheterodyne is basically a process of designing and constructing wireless communications such as radio receivers by mixing two frequencies together in order to produce a different frequency component called as intermediate frequency (IF) so as to reduce signal frequency prior to processing.

A superheterodyne receiver usually consists of an antenna, RF amplifier, mixer, local oscillator, IF amplifier, detector, AF amplifier and a speaker.

The working of a superheterodyne receiver is explained with the help of the block diagram given below in fig 1

Along with the wave form at the φ of each block



VVI

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Fig-1. Superheterodyne receiver

- In the Superheterodyne receiver, the Incoming signal through the antenna is filtered to reject the Image frequency and then amplified by the RF amplifier.
- RF amplifier can be tuned to select and amplify a particular carrier freq. within the AM broadcast range, only the select frequency and its two sidebands are allowed to pass through the amplifier.
- The carrier of the received signal is called mod frequency carrier and its frequency is mod freq = f_{RF} and the local oscillator signal operates at f_{osc} . The amplified RF frequency is then mixed with the local oscillator freq.
- The combining of these two signals is done at the mixer which produces sum & difference freq signals of the incoming carrier signal and local oscillator signal, which are

$$f_{osc} + f_{RF} \text{ \& \ } f_{osc} - f_{RF}$$

- The sum frequency ($f_{osc} + f_{RF}$) is rejected by the filter & the remaining difference freq ($f_{osc} - f_{RF}$) signal, which is a down converted frequency signal is called as Intermediate freq (IF) carrier ($f_{IF} = f_{osc} - f_{RF}$)

new idea of the superheterodyne receiver is to reduce the high frequency radio components of the incoming carrier to a fairly low, fixed value such as to be processed at the different stages of the receiver, & also to provide good stability, gain & proper selectivity and fidelity.

The modulation of the IF carrier signal is same as that of the original carrier signal & it has a fixed frequency of 455 KHz which is amplified by one or more stages of amplification.

The IF signal is amplified with the help of IF amplifier which raises its level for the information extraction process. Also the IF amplifier fulfills most of the gain and bandwidth requirements of the receiver.

IF amplifier operations are independent to the frequency at which receiver is tuned, maintaining the selectivity & sensitivity of the superheterodyne receiver considerably constant throughout the tuning range of the receiver.

This amplified IF signal is applied to the detector to detect the information signal component from 455 KHz IF, to reproduce the original information signal, which is generally in the form of audio signal.

The detector stage eliminates one of the side bands which is still present & separates the RF from the audio components of the other

- The RF component is filtered out and audio is supplied to the audio stage for magnification.
- The generated audio signal is then applied to the IF amplifier in order to increase the audio frequency level of the signal & to provide enough gain to drive the speaker or headphones.
- A speaker is connected to the AF amplifier to play the audio information signal.
- An important part of superheterodyne receiver is Automatic gain control (AGC) which is given to the RF & mixer stages in order to generate constant % irrespective of the varying IP signal.

• Superheterodyne radio receiver is spite of being more complicated than some of the other receiver offers many advantages in terms of performance, most importantly the selectivity. It is more efficiently able to remove unwanted and distracting signals than other forms like TRF & regenerative receivers.

Due to the enormous advantages provided by the superheterodyne receiver compared to the other radio receivers, they are widely used in all broadcast radio receivers, commercial radio as well as television operate on the basis of the superheterodyne principle.

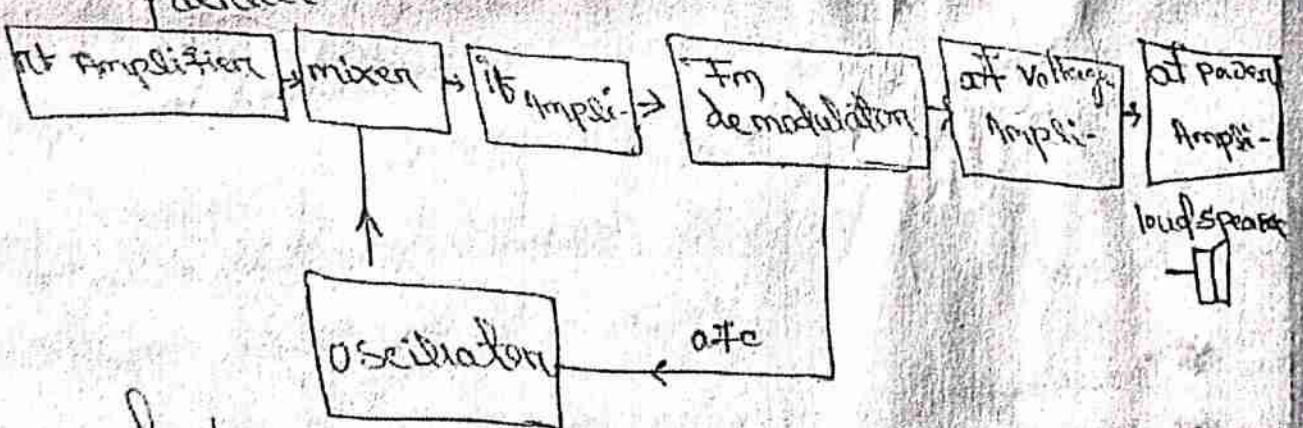
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A superheterodyne receiver usually consists of an antenna RF amplifier, mixer, local oscillator, IF amplifier, detector, AF amplifier & a speaker.

The working of a superheterodyne receiver is explained with the help of the block diagram given below in fig 1 along with the wave forms at the o/p of each block.

Block Diagram F.M Receiver
Tutorial
Aerial

02/09/20
22-108



Most of these blocks are discussed individually and in more details on other pages.

See filters, mixers, frequency changers, AM modulation & demodulation.

4/8
⇒ The f.m. band covers 88-108 MHz

⇒ There are signals from many radio transmitters in this band including signal voltages in the Aerial.

⇒ The IF amplifier selects & amplifies the desired station from the many.

⇒ It is adjustable so that the selection frequency can be altered.

⇒ This is called TUNING.

• This makes the design and operation of the amplifier much simpler.

• The amplified i.f. signal is fed to the demodulator

• This circuit recovers the audio signal & discards the r.f. carrier.

• Some of the audio is fed back to the oscillator as an AUTOMATIC FREQUENCY CONTROL voltage.

This ensures that the oscillator frequency is stable in spite of temperature changes.

• The audio signal voltage is increased in amplitude by a voltage amplifier.

• The power level is increased sufficiently to drive the loud speaker by the power amplifier.

• The cheaper receivers the tuning is fixed and

• the tuning filter is wide enough to pass all signals in the f.m. band.

* The selected frequency is applied to the mixer

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The O/P of an oscillator is also applied to the mixer
* The mixer & oscillator form a FREQUENCY CHANGER circuit.

* The O/P from the mixer is the Intermediate freq (IF)

* The IF is a fixed frequency of 10.7 MHz

* No matter what the frequency of the selected radio station is the IF is always 10.7 MHz

* The IF signal is fed into the IF Amplifier.

* The advantage of the IF amplifier is that its frequency & bandwidth are fixed, no matter what the frequency of the incoming signal is.

Key Concept:-

Concept of Frequency Conversion, RF amplification & IF Amplifier, Tuning S/N ratio.

Frequency Conversion:-

- A freq. changer an electronic device that convert alternating current (AC) of one frequency to alternating current of another frequency
- A Heterodyne is used in signal electronics to convert a freq.

RF Amplifier:-

A RF amplifier is a type of electronics amplifier that convert a low-power radio frequency signal into a higher power signal.

Typically, RF power amplifiers drive the antenna of a transmitter.

IF Amplifier:

Intermediate freq. amplifiers are amplification stages used to raise signal levels in radio & television receivers, at freq.

Intermediate to the higher radio freq. signal from the antenna & the power audio or video freq. that the receiver is receiving.

Tuning:

To adjust (an electronic receiver) to a desired freq. To adjust (an electronic circuit) so as to make it resonant with a given frequency "signal". To adjust (an engine, for ex) for max usability or performance.